

FINAL Solutions

June 9, 2009

Problem 1. (14 points) Sketch the Nyquist diagrams for the following systems.

a) (2 points) $G(s) = \frac{2s+1}{s^2(s+1)}$

b) (2 points) $G(s) = \frac{s-5}{(s+1)^2}$

c) (2 points) $G(s) = \frac{1}{s^2(s^2+3s+1)}$

d) (3 points) $G(s) = \frac{s^2+s+1}{(s-1)^2(s+1)}$

e) (5 points) $G(s) = \frac{2s-3}{(s+8)(s^2-2s+3)}$

In each case, using Nyquist stability criterion, determine *exactly* the interval for the gain K such that the negative feedback loop of $G(s)$ and K is asymptotically stable.

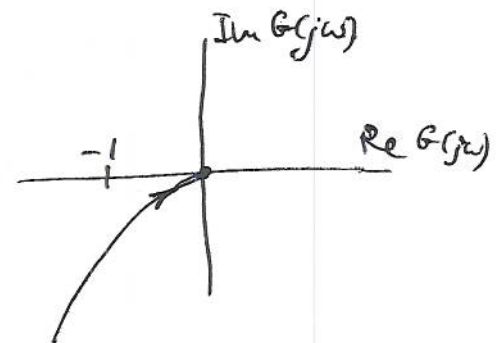
(a) $G(j\omega) = \frac{2j\omega+1}{- \omega^2(j\omega+1)} = \frac{-1-2\omega^2-j\omega}{\omega^2(\omega^2+1)}$

$\text{Re } G(j0) = -\infty$; $\text{Im } G(j0) = -\infty$

$\text{Re } G(j\infty) = -0$; $\text{Im } G(j\infty) = -0$

No intersections with axes.

Stable for all $K > 0$



(b) $G(j\omega) = \frac{j\omega-5}{(j\omega+1)^2} = \frac{j\omega-5}{1-\omega^2+2j\omega} = \frac{(j\omega-5)(1-\omega^2-2j\omega)}{(1-\omega^2)^2+4\omega^2} = \frac{7\omega^2-5+j\omega(11-\omega^2)}{(1-\omega^2)^2+4\omega^2}$

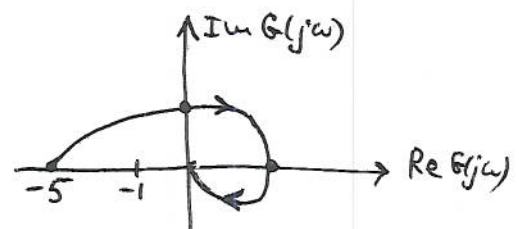
$\text{Re } G(j0) = -5$, $\text{Im } G(j0) = 0$

$\text{Re } G(j\infty) = +0$; $\text{Im } G(j\infty) = -0$

$\text{Re } G(j\omega_1) = 0 \Rightarrow \omega_1 = \sqrt{\frac{5}{7}} \Rightarrow \text{Im } G(j\omega_1) = 2.96$

$\text{Im } G(j\omega_2) = 0 \Rightarrow \omega_2 = \sqrt{11} \Rightarrow \text{Re } G(j\omega_2) = \frac{1}{2}$

Stable for $K < \frac{1}{5}$

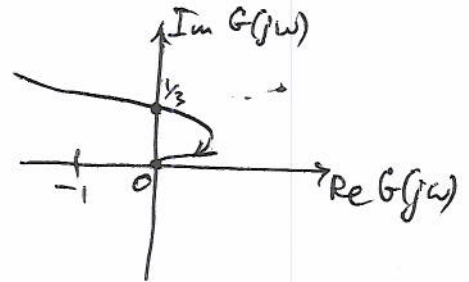


$$1(c) \quad G(j\omega) = \frac{-1}{\omega^2(1-\omega^2+3j\omega)} = \frac{\omega^2-1+3j\omega}{\omega^2((1-\omega^2)^2+9\omega^2)}$$

$$\operatorname{Re} G(j0) = -\infty; \quad \operatorname{Im} G(j0) = +\infty$$

$$\operatorname{Re} G(j\infty) = +0; \quad \operatorname{Im} G(j\infty) = +0$$

$$\text{Intersection: } \operatorname{Re} G(j\omega_1) = 0 \Rightarrow \omega_1 = 1 \\ \Rightarrow \operatorname{Im} G(j\omega_1) = \frac{1}{3}$$



Unstable for all K

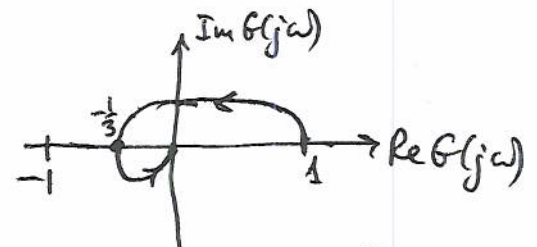
$$1(d) \quad G(j\omega) = \frac{1-\omega^2+j\omega}{(j\omega+1)(j\omega-1)^2} = \frac{1-\omega^2+j\omega}{1+\omega^2-j\omega(1+\omega^2)} = \frac{(1-\omega^2+j\omega)(1+j\omega)}{(1+\omega^2)(1+\omega^2)} \\ = \frac{1-2\omega^2+j\omega(2-\omega^2)}{(1+\omega^2)^2}$$

$$\operatorname{Re} G(j0) = 1; \quad \operatorname{Im} G(j0) = 0$$

$$\operatorname{Re} G(j\infty) = -0; \quad \operatorname{Im} G(j\infty) = -0$$

$$\text{Intersections: } \operatorname{Re} G(j\omega_1) = 0 \Rightarrow \omega_1 = \frac{1}{\sqrt{2}} \Rightarrow \operatorname{Im} G(j\omega_1) = \frac{\sqrt{2}}{3}$$

$$\operatorname{Im} G(j\omega_2) = 0 \Rightarrow \omega_2 = \sqrt{2} \Rightarrow \operatorname{Re} G(j\omega_2) = -\frac{1}{3}$$



Stable for $K > 3$ (2 unstable open-loop poles, 1 ccw encirclement for $K > 3$)

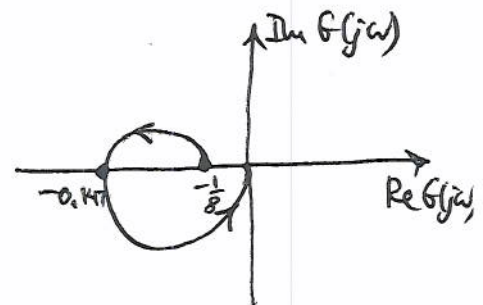
$$1(e) \quad G(j\omega) = \frac{2j\omega-3}{(j\omega+8)(3-\omega^2-2j\omega)} = \\ = \frac{-2\omega^4-8\omega^2-72+j\omega(9-15\omega^2)}{36(\omega^2-4)^2+\omega^2(\omega^2+13)^2}$$

$$\operatorname{Re} G(j0) = -\frac{1}{8}; \quad \operatorname{Im} G(j0) = 0$$

$$\operatorname{Re} G(j\infty) = -0; \quad \operatorname{Im} G(j\infty) = -0$$

$$\operatorname{Re} G(j\omega) = 0 \Rightarrow \text{no solutions because } \omega^4+4\omega^2+36=0 \Rightarrow \omega^2 = -2 \pm \sqrt{-32} \text{ not physical}$$

$$\operatorname{Im} G(j\omega_1) = 0 \Rightarrow \omega_1 = \frac{3}{\sqrt{15}} \text{ (besides } \omega=0) \Rightarrow \operatorname{Re} G(j\omega_1) = -0.147$$



Two open-loop unstable poles: $s = 1 \pm j\sqrt{2}$

One ccw encirclement: when -1 is between

$$-K \cdot 0.147 < -1 < -K \cdot \frac{1}{8} \Rightarrow \dots$$

Stable for
 $6.8 < K < 8$

Problem 2. (8 points)

Consider the system

$$G(s) = \frac{K}{s(s+1)(s+3)}$$

in the negative unity feedback loop.

Using the Nyquist diagram,

(a) (4 points) Find K for which the gain margin (GM) is exactly 2.

(b) (4 points) Find K for which the phase margin (PM) is exactly 45 degrees.

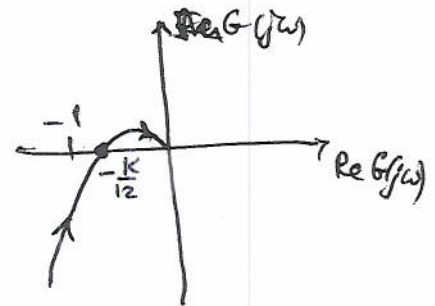
$$\begin{aligned} (a) \quad G(j\omega) &= \frac{K}{j\omega(j\omega+1)(j\omega+3)} = \frac{-Kj}{\omega(3-\omega^2+4j\omega)} \\ &= \frac{-Kj(3-\omega^2-4j\omega)}{\omega((3-\omega^2)^2+16\omega^2)} = \frac{-4K\omega + jK(\omega^2-3)}{\omega((3-\omega^2)^2+16\omega^2)} \end{aligned}$$

$$\operatorname{Re} G(j0) = -\frac{4}{9}K ; \quad \operatorname{Im} G(j0) = -\infty$$

$$\operatorname{Re} G(j\infty) = -0 ; \quad \operatorname{Im} G(j\infty) = +0$$

$$\text{Intersection: } \operatorname{Im} G(j\omega_1) = 0 \Rightarrow \omega_1 = \sqrt{3} \Rightarrow \operatorname{Re}(j\omega_1) = -\frac{K}{12}$$

$$-\frac{1}{\text{GM}} = -\frac{K}{12} \Rightarrow K = \frac{12}{2} = 6.$$



$$(b) \quad \tan(\pi + \text{PM}) = \frac{\omega_0^2 - 3}{-4\omega_0} = \frac{3 - \omega_0^2}{4\omega_0}$$

$$\tan(\pi + \frac{\pi}{4}) = 1 \Rightarrow \omega_0^2 + 4\omega_0 - 3 = 0$$

$$\omega_0 = -2 \pm \sqrt{7} \Rightarrow \omega_0 = \sqrt{7} - 2 \approx 0.646$$

$$|G(j\omega_0)|^2 = 1 \Rightarrow \frac{K^2(16\omega_0^2 + (\omega_0^2 - 3)^2)}{\omega_0^2((3 - \omega_0^2)^2 + 16\omega_0^2)^2} = 1$$

$$\Rightarrow K = \omega_0 \sqrt{16\omega_0^2 + (\omega_0^2 - 3)^2} \approx 2.359$$

Problem 3. (8 points) The general form of the lead compensator is

$$G(s) = K \frac{1 + T_1 s}{1 + T_2 s},$$

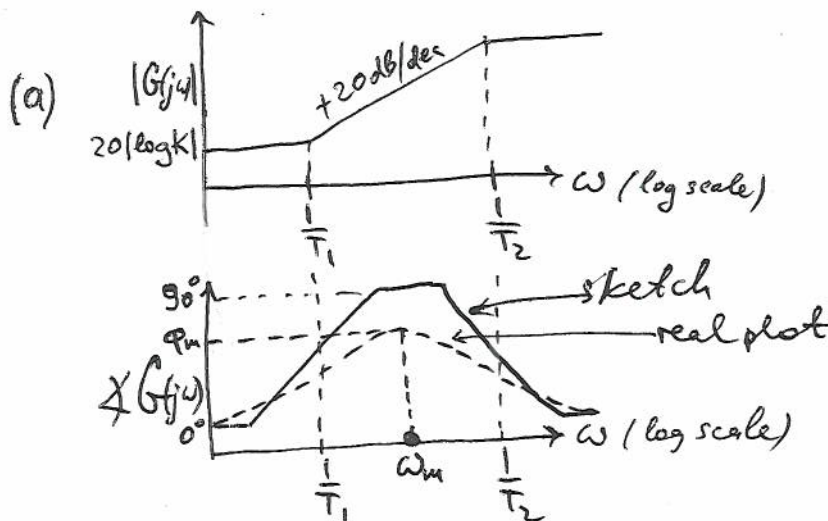
where $T_1 > T_2$.

(a) (2 points) Sketch the Bode plots of $G(s)$.

(b) (5 points) From the Bode plots you can see that there is a maximum phase advance at the particular frequency. Find this frequency and the maximum phase advance.

Hint: First derive the equation $\tan(\phi(\omega)) = f(\omega)$, ϕ being the phase (don't use the sketch obtained in (a), derive the exact expression from $G(s)$); since $\tan(\phi)$ is monotonically increasing function of ϕ , the same frequency maximizes $f(\omega)$ and $\phi(\omega)$, so it is sufficient to find the maximum of $f(\omega)$ by differentiating $f(\omega)$ w.r.t. ω and setting the result to zero; find ω from this equation and calculate the corresponding phase.

(c) (1 point) What is the maximum phase advance if T_1 and T_2 are separated by a decade, i.e. $T_1 = 10T_2$?



$$(b) \quad G(j\omega) = K \frac{1 + T_1 j\omega}{1 + T_2 j\omega} = K \frac{(1 + T_1 j\omega)(1 - T_2 j\omega)}{1 + T_2^2 \omega^2} = K \frac{1 + T_1 T_2 \omega^2 + j\omega(T_1 - T_2)}{1 + T_2^2 \omega^2}$$

$$\tan \phi = \frac{\omega(T_1 - T_2)}{1 + T_1 T_2 \omega^2} = f(\omega).$$

$$f'(\omega) = \frac{(T_1 - T_2)(1 + T_1 T_2 \omega^2) - 2T_1 T_2 \omega^2(T_1 - T_2)}{(1 + T_1 T_2 \omega^2)^2}; \quad f'(\omega_m) = 0$$

$$\Rightarrow 1 + T_1 T_2 \omega_m^2 = 2T_1 T_2 \omega_m^2 \Rightarrow \omega_m = \frac{1}{\sqrt{T_1 T_2}} \Rightarrow \tan \phi_m = \frac{T_1 - T_2}{2\sqrt{T_1 T_2}}$$

$$\phi_m = \tan^{-1} \left[\frac{T_1 - T_2}{2\sqrt{T_1 T_2}} \right]$$

$$(c) \quad \phi_m = \tan^{-1} \left[\frac{10T_2 - T_2}{2\sqrt{10T_2^2}} \right] = \tan^{-1} \left(\frac{9}{2\sqrt{10}} \right) = 0.958 \Rightarrow \phi_m = 54.9^\circ$$